DC-SQUID readout with high dynamic range and intrinsic frequency-division multiplexing capability

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dc-SQUID basics

dc-SQUID = magnetic flux to voltage/current converter



- **periodic** $V/I \Phi$ characteristic
- linear flux range: $\Phi_{lin} \sim \Phi_0 / \pi$ \longrightarrow flux-locked loop
- intrinsically 'infinitely' large dynamic range
- very high signal bandwidth: *R/L* ~ 100 GHz

flux-locked loop (FLL)

overall flux in SQUID is kept constant by applying flux feedback compensating variations caused by input signal



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disadvantages / challenges:

cable delay t_d \rightarrow FLL bandwidth < intrinsic SQUID bandwidth • slew rate $(1-10\Phi_0/\mu s)$ integrator \rightarrow automatic reset for preventing FLL running into saturation slew rate limitation! AD-converter

analog-to-digital converter (ADC)

FLL-output signal has to be compatible with input range of digitizer



signals smaller than the Least Significant Bit (LSB) can not be resolved

analog-to-digital converter (ADC)

dynamic range: ratio between largest and smallest value a quantity takes

DNR =
$$20 \log \left(\frac{2\Phi_{\text{max}}}{\Phi_{\text{noise}} \sqrt{\Delta f}} \right)$$

ADC resolution: number of discrete values over the fullrange of analog values

$$\Delta V_{
m ADC} = rac{V_{
m max} - V_{
m min}}{2^M}$$
 M: ADC resolution (#bits)

example: SQUID with $VS_{\Phi} \simeq 0.1 \,\mu \Phi_0 / \,VHz$, $\Delta f_{\rm FLL} \simeq 10 \,\rm kHz$

| $\Phi_{\sf max}$ | $1\Phi_0$ | $100\Phi_{0}$ | $10.000 \Phi_0$ |
|------------------|-----------|---------------|------------------|
| M_{\min} | 18 bit | 25 bit | 31 bit |
| DNR | 186 dB | 226 dB | 266 dB |

high requirements on ADC performance

many possibilities to increase dynamic range...

... e.g. flux counting electronics, digitial SQUIDs, SQIFs, SQUADs, SQUID cascades ...



3 dc-SQUIDs with different input sensitivity + 3 FLL-electronics and 3 digitzier used



flux ramp modulation

application of sawtooth-shaped current signal results in periodic SQUID characteristics



K. W. Lehnert *et al.*, IEEE Trans. Appl. Supercond., **17** (2007) 705
 J. A. B. Mates *et al.*, Appl. Phys. Lett. **92** (2008) 023514
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flux ramp modulation

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phase of SQUID characteristic linear measure of input signal

dynamic range not limited by ADC resolution + range

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experimental setup for proof-of-concept



linearity and dynamic range

application of flux ramp with 1 MHz repetition rate and 4.2 Φ_0 amplitude



measurement of input signal with amplitudes between $100 \,\mathrm{m}\Phi_0$ and $2500 \,\Phi_0$

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proof-of-concept: HDFRMux1

flux ramp modulation based four-channel dc-SQUID multiplexer



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proof-of-concept: HDFRMux1



M_{mod} adjusted by varying overlap between SQUID washer and modulation coil

HDFRMux1 – modulation demonstration

1 kHz flux ramp repetition rate



different carrier frequencies clearly visible in spectrum of output signal

performance of HDFRMux1 – multiplexing capability

different signal on SQUID inputs, 250 kHz flux ramp repetition rate



successful demonstration of flux ramp modulation based dc-SQUID multiplexing technique

performance of HDFRMux1 – crosstalk

10 kHz sinusoidal signal in SQ2, 250 kHz flux ramp repetition rate



measured crosstalk between channels < 0.5 %

summary and outlook



novel dc-SQUID readout technique

- 'infinitely' large dynamic range
- no slew rate limitations
- MHz frequency domain multiplexing capability



what's next?

- 'optimized' devices
- Further reduce crosstalk in FRM-muxing
- readout noise optimization (preamplifier)
- dedicated readout electronics (FPGA based)

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thank you for your attention!